

THE MATHS/COMPUTER SCIENCE  
TALK

# RESOURCE CONSTRAINED-MOBILE ROBOTICS

PROFESSOR TAUHIDUL ALAM

WEDNESDAY 11/14  
COMMON HOUR  
NAB 2123

*A bouncing robot is equipped with an internal clock and bump or contact sensors. How can we generate a navigation path of this simple robot from one location to another and plan paths to sweep an area?*



Free pizza  
will be raffled!

Sponsored by SUNY  
Old Westbury Division  
of Student Affairs